



# Machine Learning and Knowledge Graphs

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# Outline

- **Knowledge Graphs**
  - What are they?
  - Where are they?
  - Where do they come from?

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  - Black-Box Models (Latent FMs)
  - Towards Combining the Two Worlds

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- **Statistical Relational Learning in Knowledge Graphs**
  - Explainable Models (Observable FMs)
  - Black-Box Models (Latent FMs)
  - Towards Combining the Two Worlds
- **Differentiable Reasoning**

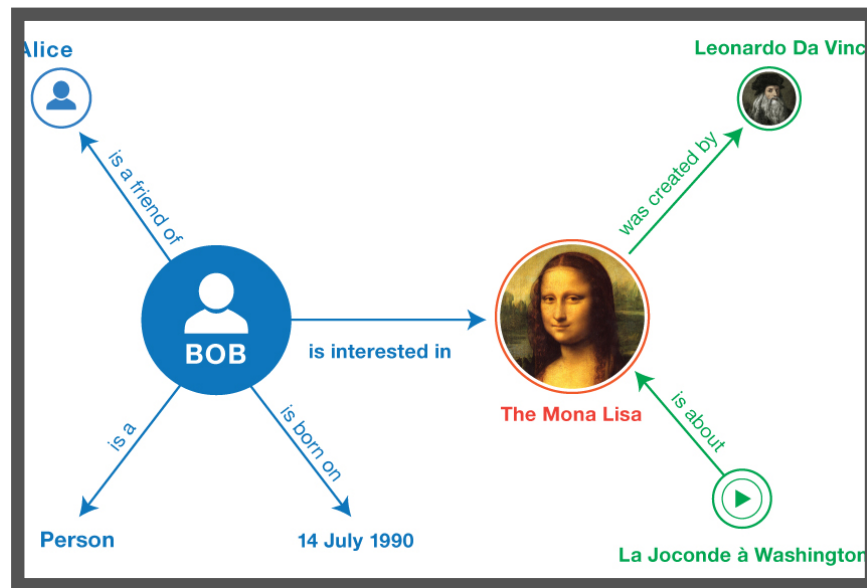
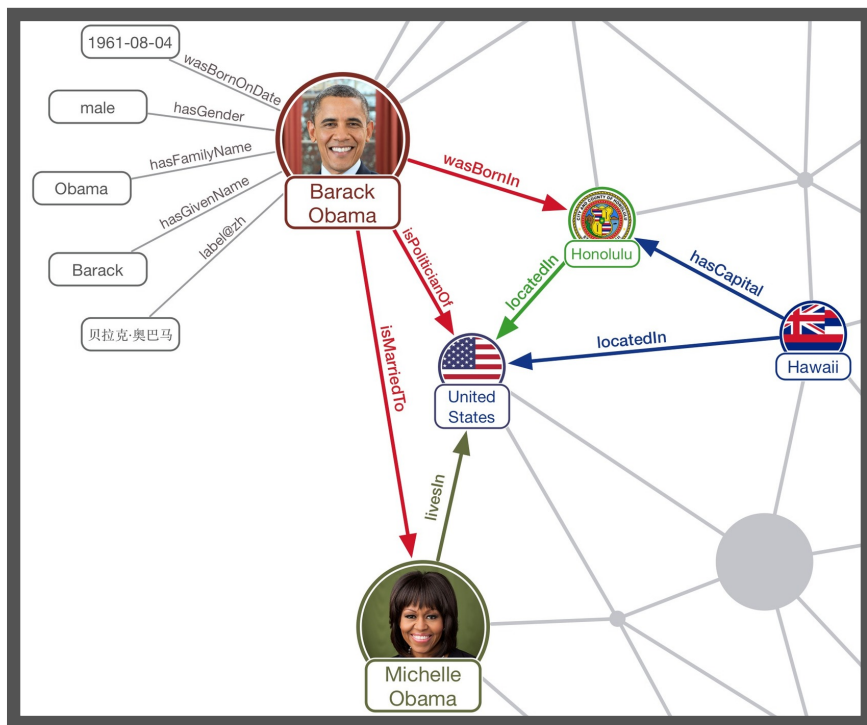


# Knowledge Graphs

**Knowledge Graphs** are *graph-structured Knowledge Bases*, where knowledge is encoded by *relationships between entities*.

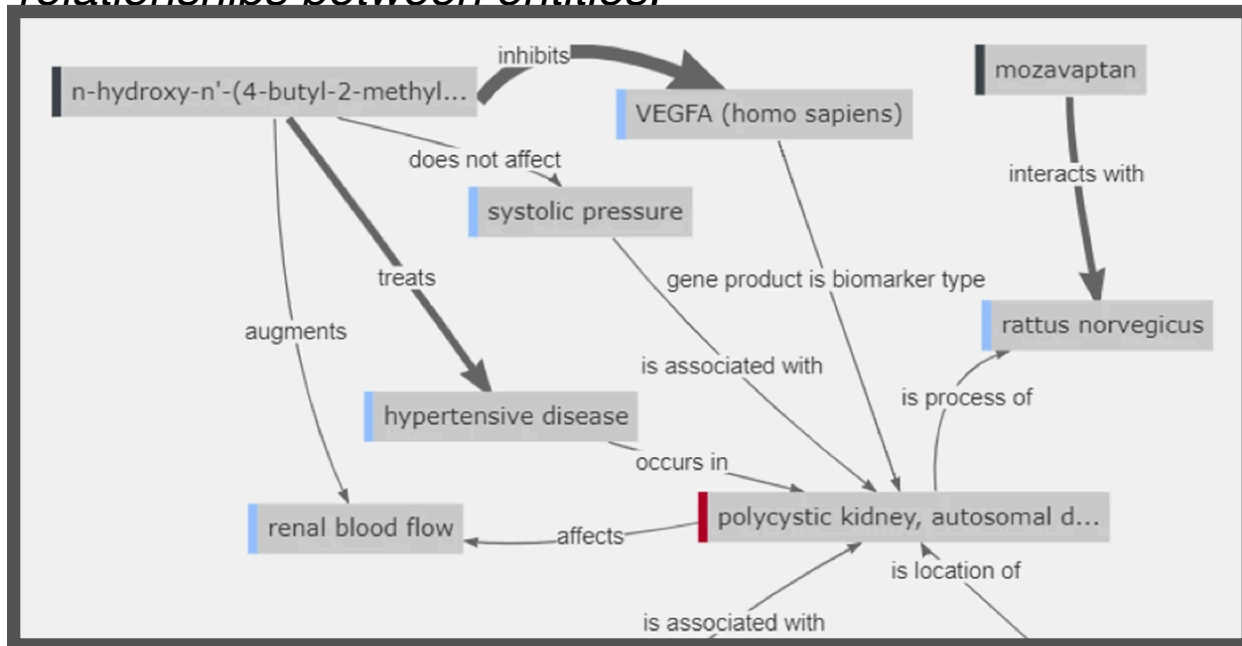
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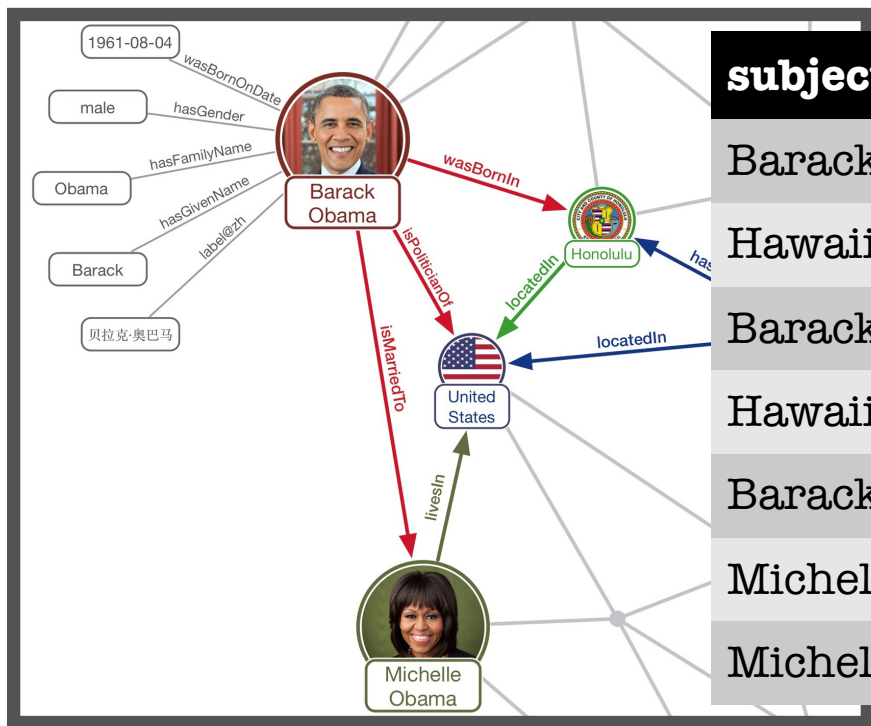
**Knowledge Graphs** are *graph-structured Knowledge Bases*, where knowledge is encoded by *relationships between entities*.



**Drug Prioritization using the semantic properties of a Knowledge Graph**, Nature 2019

# Knowledge Graphs

**Knowledge Graphs** are *graph-structured Knowledge Bases*, where knowledge is encoded by *relationships between entities*.



**subject**

**predicate**

**object**

Barack Obama

was born in

Honolulu

Hawaii

has capital

Honolulu

Barack Obama

is politician of

United States

Hawaii

is located in

United States

Barack Obama

is married to

Michelle Obama

Michelle Obama

is a

Lawyer

Michelle Obama

lives in

United States

# Industry-Scale Knowledge Graphs

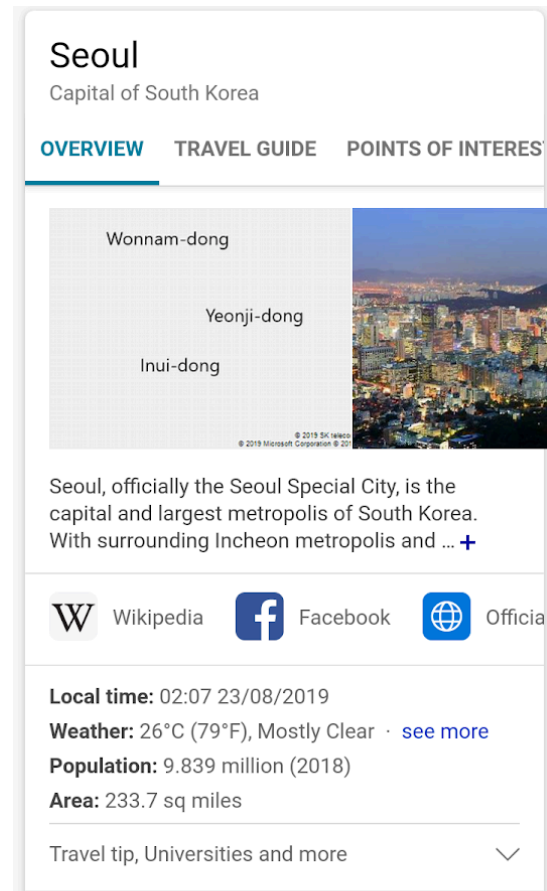
In many enterprises, Knowledge Graphs are **critical** — they provide structured data and factual knowledge that drives many products, making them more “intelligent”.

# Industry-Scale Knowledge Graphs in Microsoft

In *Microsoft* there are several major graph systems used by products:

- *Bing Knowledge Graph* — contains information about the world and powers question answering services on Bing.
- *Academic Graph* — collection of entities such as people, publications, fields of study, conferences, etc. and helps users discovering relevant research works.
- *LinkedIn Graph* — contains entities such as people, jobs, skills, companies, etc. and it is used to find economy-level insights for countries and regions.

**~2 Billion primary entities, ~55 Billion Facts**



Seoul  
Capital of South Korea

[OVERVIEW](#) [TRAVEL GUIDE](#) [POINTS OF INTEREST](#)

Wonnam-dong  
Yeonji-dong  
Inui-dong

Seoul, officially the Seoul Special City, is the capital and largest metropolis of South Korea. With surrounding Incheon metropolis and ... +

[W](#) Wikipedia [f](#) Facebook [globe](#) Official

**Local time:** 02:07 23/08/2019  
**Weather:** 26°C (79°F), Mostly Clear · [see more](#)  
**Population:** 9.839 million (2018)  
**Area:** 233.7 sq miles

Travel tip, Universities and more

# Industry-Scale Knowledge Graphs in Google

The *Google Knowledge Graph* contains more than 70 billion assertions describing a billion entities and covers a variety of subject matter — “things not strings”.

Used for answering factoid queries about entities served from the Knowledge Graph.

**1 Billion entities, ~70 Billion assertions**



## Seoul

Capital of South Korea

Seoul, the capital of South Korea, is a huge metropolis where modern skyscrapers, high-tech subways and pop culture meet Buddhist temples, palaces and street markets. Notable attractions include futuristic Dongdaemun Design Plaza, a convention hall with curving architecture and a rooftop park. Gyeongbokgung Palace, which once had more than 7,000 rooms, is a palace of ancient locust and pine trees.

**Area:** 605.2 km<sup>2</sup>

**Elevation:** 38 m

**Local time:** Friday 03:14

**Weather:** 23 °C, Wind NW at 2 mph

**Population:** 9.776 million (2017) Units

population in Seoul

[All](#) [Images](#) [News](#) [Maps](#)

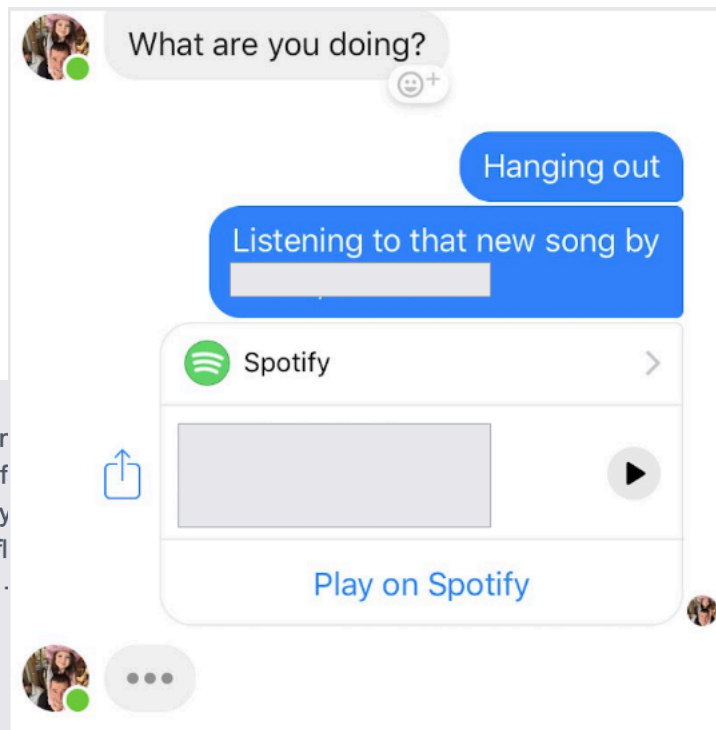
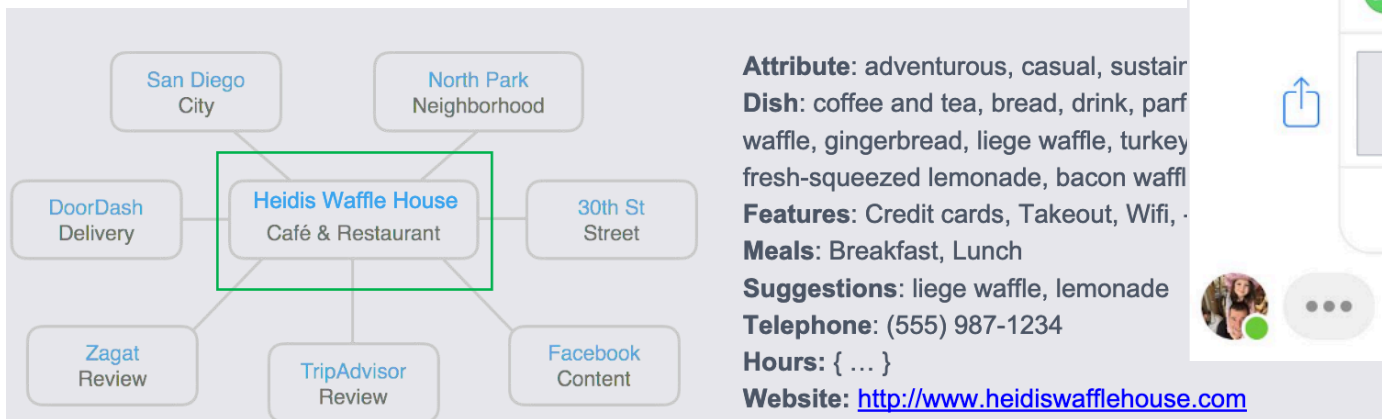
About 230,000,000 results (0.66 seconds)

Seoul / Population

**9.776 million (2017)**

# Industry-Scale Knowledge Graphs in Facebook

World's largest social graph — *Facebook's Knowledge Graph* focuses on socially relevant entities, such as celebrities, places, movies, and music. Used to *recommend smart replies, entity detection, and easy sharing.*



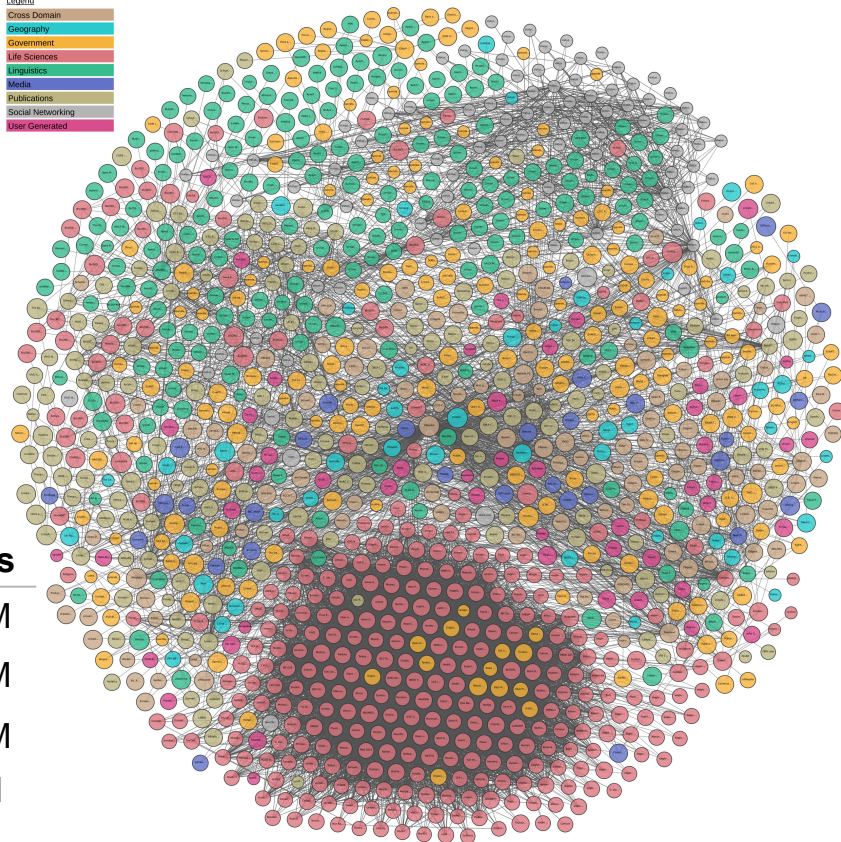
**~50 million primary entities, ~500 million assertions**



# The Linked Open Data Cloud

**Linked Open Data cloud** - over 1200 interlinked KGs encoding more than 200M facts about more than 50M entities.

Spans a variety of domains, such as Geography, Government, Life Sciences, Linguistics, Media, Publications, and Cross-domain

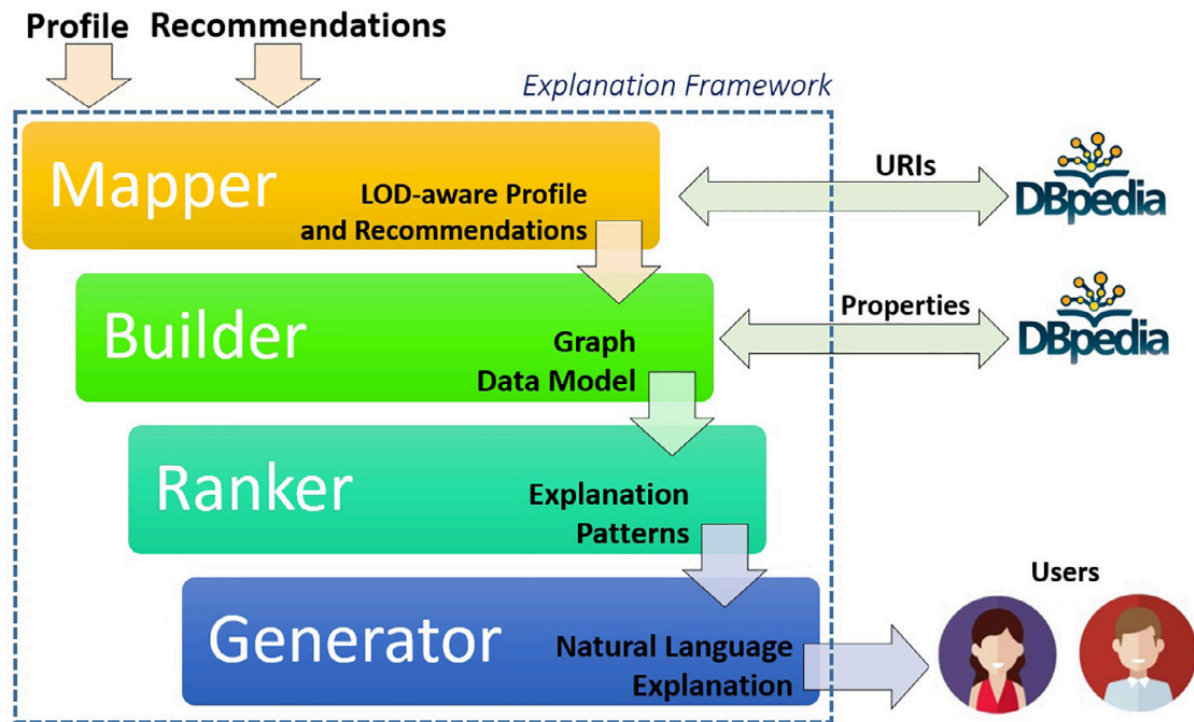


Name	Entities	Relations	Types	Facts
Freebase	40M	35K	26.5K	637M
DBpedia (en)	4.6M	1.4K	735	580M
YAGO3	17M	77	488K	150M
Wikidata	15.6M	1.7K	23.2K	66M

# Knowledge Graphs and Explainable AI

We can use Knowledge Graphs for *explaining* the decisions of Machine Learning algorithms, such as recommender systems, and design machine learning models that are less prone to capturing *spurious correlations* in the data.

- Locally vs. Globally
- Ad-hoc vs. Post-hoc

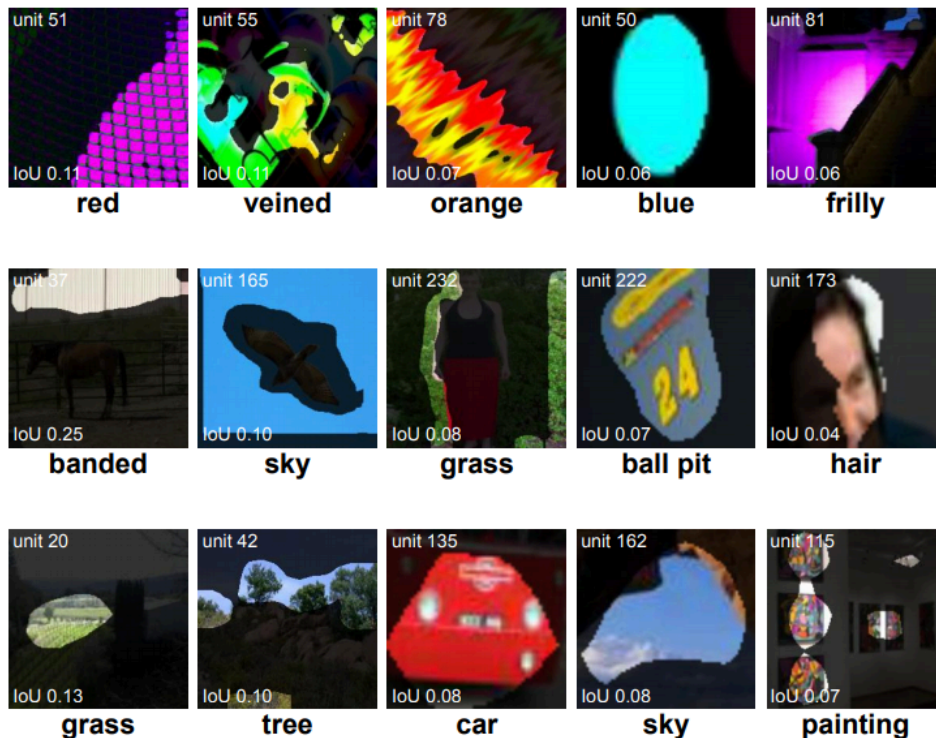


LOD-based Explanations for Transparent Recommender Systems - IJHCS  
Linked Open Data to Support Content-Based Recommender Systems - ICSS  
Top-n recommendations from implicit feedback leveraging linked open data - RECSYS

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**Network Dissection: Quantifying Interpretability of Deep Visual Representations  
On the Role of Knowledge Graphs in Explainable AI - SWJ**

# Knowledge Graphs and Explainable AI

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## Annotation Artifacts in Natural Language Inference Data

Suchin Gururangan<sup>★◇</sup> Swabha Swayamdipta<sup>★♥</sup>  
Omer Levy<sup>★</sup> Roy Schwartz<sup>★♣</sup> Samuel R. Bowman<sup>†</sup> Noah A. Smith<sup>★</sup>

## Performance Impact Caused by Hidden Bias of Training Data for Recognizing Textual Entailment

Masatoshi Tsuchiya

## Behavior Analysis of NLI Models: Uncovering the Influence of Three Factors on Robustness

V. Ivan Sanchez Carmona and Jeff Mitchell and Sebastian Riedel

## Hypothesis Only Baselines in Natural Language Inference

Adam Poliak<sup>1</sup> Jason Naradowsky<sup>1</sup> Aparajita Haldar<sup>1,2</sup>  
Rachel Rudinger<sup>1</sup> Benjamin Van Durme<sup>1</sup>

On the Role of Knowledge Graphs in Explainable AI - SWJ  
Dynamic Integration of Background Knowledge in Neural NLU Systems

# Knowledge Graphs Construction

Knowledge Graph construction methods can be classified in:

- **Manual** — curated (e.g. via experts), collaborative (e.g. via volunteers)
- **Automated** — semi-structured (e.g. from infoboxes), unstructured (e.g. from text)

Coverage is an issue:

- **Freebase** (40M entities) - 71% of persons without a birthplace, 75% without a nationality, even worse for other relation types [Dong et al. 2014]
- **DBpedia** (20M entities) - 61% of persons without a birthplace, 58% of scientists missing why they are popular [Krompaß et al. 2015]

**Relational Learning** can help us overcoming these issues and - in general - with learning from relational representations.

# Relational Learning in Knowledge Graphs

- **Dyadic Multi-Relational Data** [Nickel et al. 2015, Getoor et al. 2007]
- Many possible relational learning tasks:
  - **Link Prediction** — Identify missing relationships between entities
  - **Collective Classification** — Classify entities based on their relationships
  - **Link-Based Clustering** — Cluster entities based on their relationships
  - **Entity Resolution** — Entity mapping/deduplication

Relational structure is a rich source of information.

In general, the *i.i.d. assumption* does not hold in this context.



# Statistical Relational Learning

**Task** — model the existence of each triple  $x_{spo} = (s, p, o) \in \mathcal{E} \times \mathcal{R} \times \mathcal{E}$  as *binary random variables*  $y_{spo} \in \{0,1\}$  indicating whether  $x_{spo}$  is in the KG:

$$y_{spo} = \begin{cases} 1 & \text{if } x_{spo} \in \mathcal{G} \\ 0 & \text{otherwise} \end{cases} \quad \text{entries in } \bar{\mathbf{Y}} \in \{0,1\}^{|\mathcal{E}| \times |\mathcal{R}| \times |\mathcal{E}|}$$

Every realisation of  $\bar{\mathbf{Y}}$  denotes a *possible world* - modelling  $P(\bar{\mathbf{Y}})$  allows predicting triples based on the state of the entire Knowledge Graph.

Scalability is important - e.g. on Freebase (40M entities), the number of variables to represent can be quite large:  $|\mathcal{E} \times \mathcal{R} \times \mathcal{E}| > 10^{19}$

# Types of Statistical Relational Learning Models

Depending on our assumptions on  $P(\bar{\mathbf{Y}})$ , we end up with *three model classes*:

- **Latent Feature Models**: variables  $y_{spo} \in \{0,1\}$  are *conditionally independent* given the *latent features*  $\Theta$  associated with subject, predicate, and object:

$$\forall x_i, x_j \in \mathcal{E} \times \mathcal{R} \times \mathcal{E}, x_i \neq x_j : y_i \perp\!\!\!\perp y_j \mid \Theta$$

- **Observable Feature Models**: related to Latent Feature Models, but  $\Theta$  are now *graph-based features*, such as *paths* linking the subject and the object.
- **Graphical Models**: variables  $y_{spo} \in \{0,1\}$  are not assumed to be conditionally independent — each  $y_{spo}$  can depend on any of the other random variables in  $\bar{\mathbf{Y}}$ .



# Conditional Independence Assumption

Assuming all  $y_{spo}$  variables are conditionally independent allows modelling their existence via a *scoring function*  $f(s, p, o | \Theta)$  representing the likelihood that a triple is in the KG, conditioned on the parameters  $\Theta$  :

$$P(\bar{\mathbf{Y}} | \Theta) = \prod_{s \in \mathcal{E}} \prod_{p \in \mathcal{R}} \prod_{o \in \mathcal{E}} \begin{cases} P(y_{spo} | \Theta) & \text{if } y_{spo} = 1 \\ 1 - P(y_{spo} | \Theta) & \text{otherwise} \end{cases} \quad \text{with } P(y_{spo} | \Theta) = \sigma(f(s, p, o | \Theta))$$

**Scoring Function** - depending on the type of features used by  $f(\cdot | \Theta)$  we have two families of models - *Observable* and *Latent Feature Models*.

# Observable Feature Models

**Uni-Relational Similarity Measures:** based on *homophily* — similar entities are likely to be related — and *neighbourhood similarity*.

- **Local:** derive similarity between entities from their local neighbourhood  
(e.g. Common Neighbours, Adamic-Adar Index [Adamic et al. 2003], Preferential Attachment [Barabási et al. 1999], ..)
- **Global:** derive similarity between entities using the whole graph  
(e.g. Katz Index [Katz, 1953], Leicht-Holme-Newman Index [Leicht et al. 2006], PageRank [Brin et al. 1998], ..)
- **Quasi-Local:** trade-off between computational complexity and predictive accuracy  
(e.g. Local Katz Index [Liben-Nowell et al. 2007], Local Random Walks [Liu et al. 2010], ..)

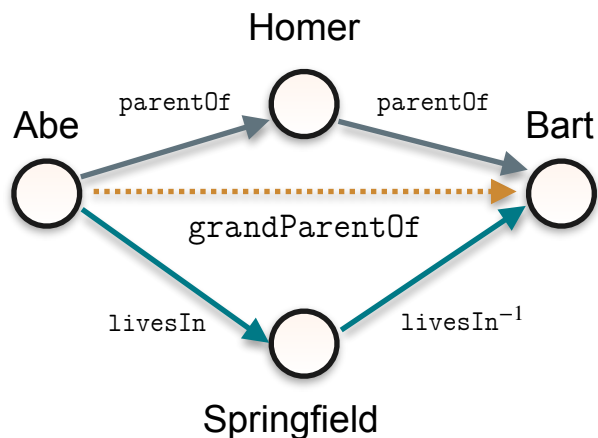
# Observable Feature Models - Rule Mining and ILP

**Rule Mining** and **Inductive Logic Programming** methods extract rules via mining methods, and use them to infer new links.

- **Logic Programming (deductive):** from facts and rules, infer new facts (First-Order Logic)
- **Inductive Logic Programming (ILP):** from correlated facts, infer new rules  
(e.g. Progol [Muggleton, 1993], Aleph [Srinivasan, 1999], DL-Learner [Lehmann, 2009], FOIL [Quinlan, 1990], ..)
- **Rule Mining:** AMIE [Galárraga et al. 2015] is orders of magnitude faster than traditional ILP methods, and consistent with the Open World Assumption in Knowledge Graphs:
  - Partial Completeness Assumption
  - Efficient search space exploration via Mining Operators

# Observable Feature Models - Path Ranking Algorithm

**Path Ranking Algorithm (PRA)** uses *length-bounded random walks* as features between entity pairs for predicting a target relation [Lao et al. 2010].



A **PRA model** scores a subject-object pair by a linear function of their path features:

$$f(s, p, o) = \sum_{\pi \in \Pi_p} P(s \rightarrow o \mid \pi) \times \theta_{\pi, p}$$

where  $\Pi$  is the set of all length-bounded relation paths, and  $\theta$  are parameters estimated via L1, L2-regularised logistic regression.

Some extensions: Subgraph Features [Gardner et al. 2015], Multi-Task [Wang et al. 2016]

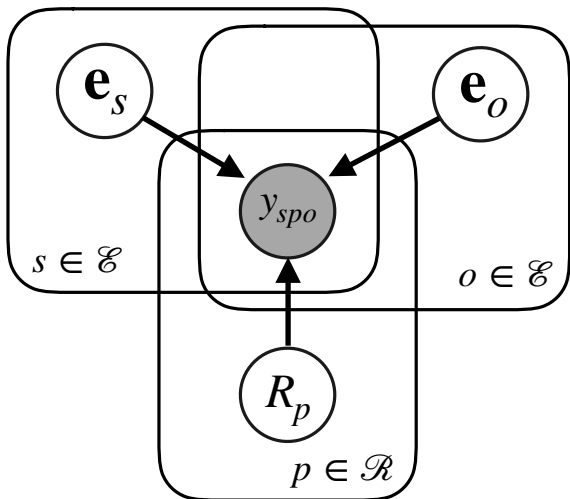
# Observable Feature Models are *Interpretable*

Rules extracted by AMIE+ [Galárraga et al. 2015] from the YAGO3-10 dataset [Dettmers et al. 2018]

Body	⇒	Head	Confidence
hasNeighbor(X, Y)	⇒	hasNeighbor(Y, X)	0.99
isMarriedTo(X, Y)	⇒	isMarriedTo(Y, X)	0.96
hasNeighbor(X, Z) ∧ hasNeighbor(Z, Y)	⇒	hasNeighbor(X, Y)	0.88
isAffiliatedTo(X, Y)	⇒	playsFor(Y, X)	0.87
playsFor(X, Y)	⇒	isAffiliatedTo(Y, X)	0.75
dealsWith(X, Z) ∧ dealsWith(Z, Y)	⇒	dealsWith(X, Y)	0.73
isConnectedTo(X, Y)	⇒	isConnectedTo(Y, X)	0.66
dealsWith(X, Z) ∧ imports(Z, Y)	⇒	imports(X, Y)	0.61
influences(Z, X) ∧ isInterestedIn(Z, Y)	⇒	isInterestedIn(X, Y)	0.53

# Latent Feature Models

Variables  $y_{spo}$  are conditionally independent given a set of latent features and parameters  $\Theta$ . *Latent* means that are not directly observed in the data, and thus need to be estimated.

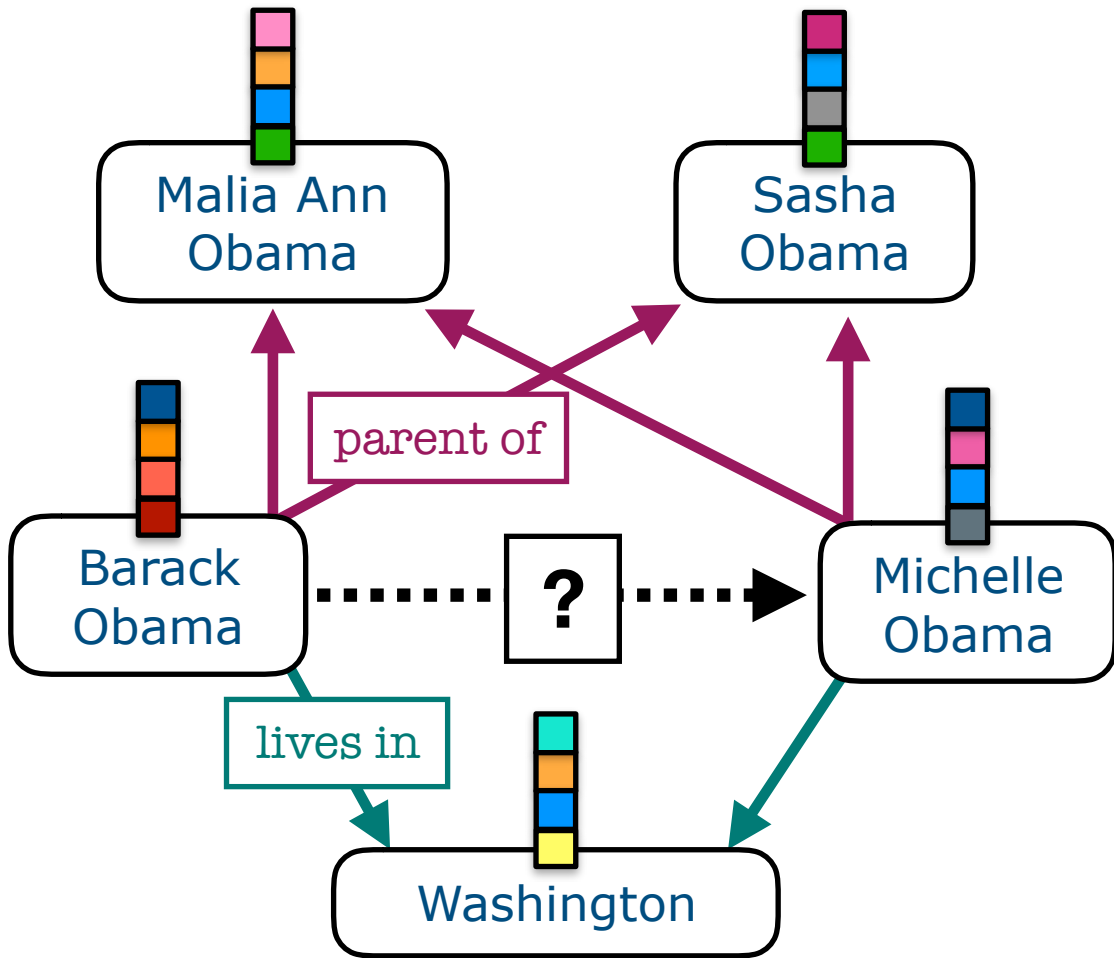


Relationships between entities  $s$  and  $o$  can be inferred from the interactions of their latent features  $\mathbf{e}_s, \mathbf{e}_o$ :

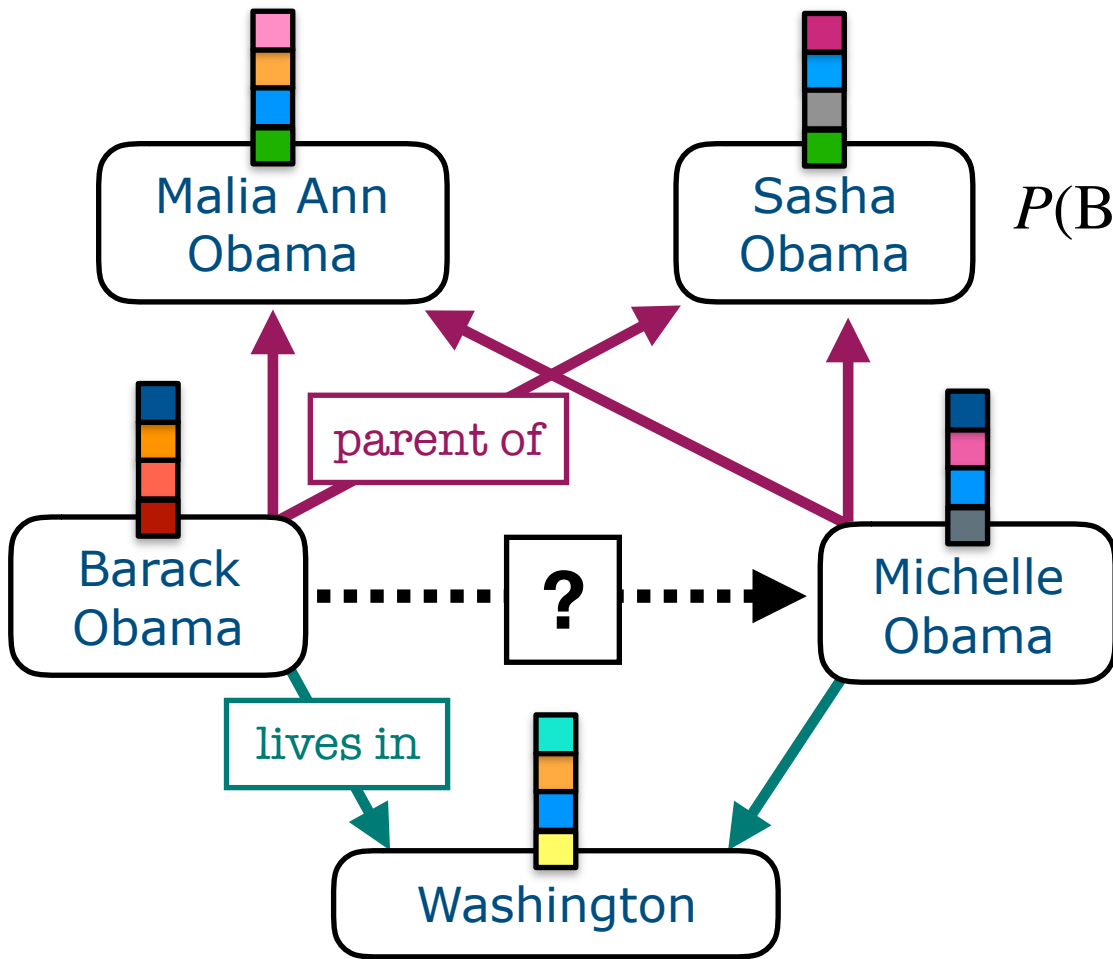
$$f(s, p, o) = f_p(\mathbf{e}_s, \mathbf{e}_o) \quad \begin{cases} \mathbf{e}_s, \mathbf{e}_o \in \mathbb{R}^k, \\ f_p : \mathbb{R}^k \times \mathbb{R}^k \mapsto \mathbb{R} \end{cases}$$

The latent features inferred by these models can be very hard to interpret.

# Latent Feature Models



# Latent Feature Models



$$P(\text{BO} \xrightarrow{\text{married}} \text{MO}) \propto$$

$$f_{\text{married}} \left( \begin{array}{c} \text{Blue} \\ \text{Orange} \\ \text{Red} \end{array}, \begin{array}{c} \text{Blue} \\ \text{Pink} \\ \text{Grey} \end{array} \right)$$

## Learning Representations

$$\mathcal{L}(\mathcal{E} | \Theta) = \sum_{(s,p,o) \in \mathcal{E}} \log \sigma \left( f_p(\mathbf{e}_s, \mathbf{e}_o) \right) + \sum_{(s,p,o) \notin \mathcal{E}} \log \left[ 1 - \sigma \left( f_p(\mathbf{e}_s, \mathbf{e}_o) \right) \right]$$



# Latent Feature Models - Scoring Functions

Relationships between entities are determined by interactions between latent features — this yields different choices for the scoring function  $f_p : \mathbb{R}^k \times \mathbb{R}^k \mapsto \mathbb{R}$  :

Models	Scoring Functions	Parameters
RESCAL [Nickel et al. 2011]	$\mathbf{e}_s^\top \mathbf{W}_p \mathbf{e}_o$	$\mathbf{W}_p \in \mathbb{R}^{k \times k}$
NTN [Socher et al. 2013]	$\mathbf{u}_p^\top f \left( \mathbf{e}_s \mathbf{W}_p^{[1 \dots d]} + \mathbf{V}_p \begin{bmatrix} \mathbf{e}_s \\ \mathbf{e}_o \end{bmatrix} + \mathbf{b}_p \right)$	$\mathbf{W}_p \in \mathbb{R}^{k^2 \times d}, \mathbf{V}_p \in \mathbb{R}^{2k \times d}, \mathbf{b}_p, \mathbf{u}_p \in \mathbb{R}^k$
TransE [Bordes et al. 2013]	$-\  \mathbf{e}_s + \mathbf{r}_p - \mathbf{e}_o \ _{1,2}^2$	$\mathbf{r}_p \in \mathbb{R}^k$
DistMult [Yang et al. 2014]	$\langle \mathbf{e}_s, \mathbf{r}_p, \mathbf{e}_o \rangle$	$\mathbf{r}_p \in \mathbb{R}^k$
HolE [Nickel et al. 2016]	$\mathbf{r}_p^\top \left( \mathcal{F}^{-1} \left[ \overline{\mathcal{F}[\mathbf{e}_s]} \odot \mathcal{F}[\mathbf{e}_o] \right] \right)$	$\mathbf{r}_p \in \mathbb{R}^k$
ComplEx [Trouillon et al. 2016]	$\text{Re} \left( \langle \mathbf{e}_s, \mathbf{r}_p, \bar{\mathbf{e}}_o \rangle \right)$	$\mathbf{r}_p \in \mathbb{C}^k$
ConvE [Dettmers et al. 2017]	$f \left( \text{vec} \left( f \left( [\bar{\mathbf{e}}_s; \bar{\mathbf{r}}_p] * \omega \right) \right) \mathbf{W} \right) \mathbf{e}_o$	$\mathbf{r}_p \in \mathbb{R}^k, \mathbf{W} \in \mathbb{R}^{c \times k}$

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HolE [Nickel et al. 2016]	$\mathbf{r}_p^\top \left( \mathcal{F}^{-1} \left[ \overline{\mathcal{F}[\mathbf{e}_s]} \odot \mathcal{F}[\mathbf{e}_o] \right] \right)$	$\mathbf{r}_p \in \mathbb{R}^k$
ComplEx [Trouillon et al. 2016]	$\text{Re} \left( \langle \mathbf{e}_s, \mathbf{r}_p, \bar{\mathbf{e}}_o \rangle \right)$	$\mathbf{r}_p \in \mathbb{C}^k$
ConvE [Dettmers et al. 2017]	$f \left( \text{vec} \left( f \left( [\bar{\mathbf{e}}_s; \mathbf{r}_p] * \omega \right) \right) \mathbf{W} \right) \mathbf{e}_o$	$\mathbf{r}_p \in \mathbb{R}^k, \mathbf{W} \in \mathbb{R}^{c \times k}$

# Latent Feature Models - Learning

Another core difference among models is the *loss function* minimised for fitting the latent parameters  $\Theta$  to the data — let  $f_{spo} = f(x_{spo} | \Theta)$  and  $p_{spo} = \sigma(f_{spo})$  :

Losses	Formulation	Models
Quadratic Loss	$\sum_{(x_{spo}, y_{spo}) \in \mathcal{D}} \ y_{spo} - f_{spo}\ _2^2$	Tensor Factorisation, RESCAL (ALS)
Pairwise Loss	$\sum_{x_+ \in \mathcal{D}_+} \sum_{x_- \in \mathcal{D}_-} \mathcal{L}(x_+, x_-) \stackrel{e.g.}{=} \max\{0, \gamma + f_{x_-} - f_{x_+}\}$	SE, NTN, TransE, HoIE
Cross-Entropy Loss	$\sum_{(x, y) \in \mathcal{D}} \left[ y \log(p_x) + (1 - y) \log(1 - p_x) \right]$	ComplEx
Multiclass Loss	$\sum_{x_{spo} \in \mathcal{D}_+} \mathcal{L}(p_{spo}, 1) + \sum_{\tilde{s} \in \mathcal{E}} \mathcal{L}(p_{\tilde{s}spo}, y_{\tilde{s}spo}) + \sum_{\tilde{o} \in \mathcal{E}} \mathcal{L}(p_{spo\tilde{o}}, y_{spo\tilde{o}})$	ConvE, ComplEx-N3 [Dettmers et al. 2017, Lacroix et al. 2018]

# Latent Feature Models - Predictive Accuracy

**Evaluation Metrics** — Area Under the Precision-Recall Curve (AUC-PR), Mean Reciprocal Rank (MRR), Hits@k. In MRR and Hits@k, for each test triple:

- Modify its subject with all the entities in the Knowledge Graph,
- Score all the triple variants, and *compute the rank* of the original test triple,
- Repeat for the object.

$$\text{MRR} = \frac{1}{|\mathcal{T}|} \sum_{i=1}^{|\mathcal{T}|} \frac{1}{\text{rank}_i}, \quad \text{HITS@}k = \frac{|\{\text{rank}_i \leq 10\}|}{|\mathcal{T}|}$$

From [Lacroix et al. ICML 2018]

Model		WN18		WN18RR		FB15K		FB15K-237		YAGO3-10	
		MRR	H@10	MRR	H@10	MRR	H@10	MRR	H@10	MRR	H@10
Reciprocal	CP-FRO	<b>0.95</b>	0.95	0.46	0.48	<b>0.86</b>	0.91	0.34	0.51	0.54	0.68
	CP-N3	<b>0.95</b>	0.96	0.47	0.54	<b>0.86</b>	0.91	0.36	0.54	0.57	<b>0.71</b>
	Complex-FRO	<b>0.95</b>	0.96	0.47	0.54	<b>0.86</b>	0.91	0.35	0.53	0.57	<b>0.71</b>
	Complex-N3	<b>0.95</b>	0.96	<b>0.48</b>	<b>0.57</b>	<b>0.86</b>	0.91	<b>0.37</b>	<b>0.56</b>	<b>0.58</b>	<b>0.71</b>

# Latent Feature Models - Interpreting the Embeddings

Learned relation embeddings — using *ComplEx* with a *pairwise margin-based loss* — for WordNet (left), DBpedia, and YAGO (right) [Minervini et al. ECML 2017]

	Real Part					Imaginary Part				
hypernym	1.0	3.0	-3.1	2.5	-2.7	3.2	2.9	1.7	-3.0	-3.0
hyponym	1.0	3.1	-3.1	2.6	-2.7	-3.4	-2.8	-1.7	2.9	3.0
synset domain topic of	-3.1	-2.7	2.2	3.2	-2.4	-3.0	-1.6	-2.9	-2.8	2.6
member of domain topic	-3.1	-2.7	2.2	3.2	-2.5	2.8	1.7	2.9	2.9	-2.6
member of domain usage	-1.4	-0.1	-2.5	-3.4	2.7	-3.0	1.8	2.6	-0.6	-1.3
synset domain usage of	-1.2	-0.1	-2.3	-3.3	2.6	3.1	-1.8	-2.5	0.7	1.4
instance hypernym	-1.1	-2.8	1.6	2.7	-2.5	3.0	-2.6	2.6	-1.1	-2.8
instance hyponym	-1.0	-2.9	1.5	2.9	-2.4	-2.9	2.8	-2.6	1.1	2.8
part of	-2.4	3.2	2.7	-1.5	3.0	-2.4	-0.6	-2.6	2.9	-1.9
has part	-2.5	3.2	2.9	-1.5	3.0	2.4	0.7	2.8	-3.0	1.9
member holonym	2.4	2.8	2.4	1.9	-2.4	2.9	-2.3	2.6	2.7	-2.4
member meronym	2.4	2.9	2.4	1.9	-2.3	-2.9	2.3	-2.5	-2.8	2.5
synset domain region of	-3.1	-0.3	3.1	-3.3	1.9	-0.9	2.0	-2.1	-1.2	1.0
member of domain region	-3.1	-0.3	3.2	-3.4	2.0	1.0	-2.1	2.2	1.3	-1.1
verb group	3.5	3.4	3.3	-1.8	-2.8	0.0	-0.1	0.0	0.0	0.0
derivationally related form	3.5	3.4	-3.2	3.4	3.2	0.0	0.0	-0.0	0.0	0.0

	Real Part					Imaginary Part				
musical artist	1.9	3.8	3.8	-1.7	-1.0	-2.5	0.4	-0.8	3.0	3.7
musical band	1.8	3.8	4.1	-1.8	-1.0	-2.5	0.3	-0.9	3.1	3.6
associated musical artist	3.7	3.2	3.7	3.4	3.3	0.7	0.1	0.2	-1.5	1.5
associated band	3.7	3.7	3.2	3.7	3.6	0.7	0.0	0.2	-1.5	1.5

	Real Part					Imaginary Part				
playsFor	3.6	-2.6	2.6	2.7	-3.1	2.5	3.0	2.8	2.6	-2.6
isAffiliatedTo	3.8	-2.6	2.6	2.6	-3.2	2.7	3.3	3.0	2.6	-2.8
hasNeighbor	0.9	2.5	2.9	3.5	2.2	0.0	-0.0	0.0	-0.1	-0.0
isMarriedTo	3.9	3.5	4.3	-2.1	0.0	0.0	-0.0	-0.0	0.0	0.0
isConnectedTo	-0.7	3.0	2.6	0.3	2.7	0.3	-0.1	-0.0	0.1	-0.0

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hyponym	1.0	3.1	-3.1	2.6	-2.7	-3.4	-2.8	-1.7	2.9	3.0
synset domain topic of	-3.1	-2.7	2.2	3.2	-2.4	-3.0	-1.6	-2.9	-2.8	2.6
member of domain topic	-3.1	-2.7	2.2	3.2	-2.5	2.8	1.7	2.9	2.9	-2.6
member of domain usage	-1.4	-0.1	-2.5	-3.4	2.7	-3.0	1.8	2.6	-0.6	-1.3
synset domain usage of	-1.2	-0.1	-2.3	-3.3	2.6	3.1	-1.8	-2.5	0.7	1.4
instance hypernym	-1.1	-2.8	1.6	2.7	-2.5	3.0	-2.6	2.6	-1.1	-2.8
instance hyponym	-1.0	-2.9	1.5	2.9	-2.4	-2.9	2.8	-2.6	1.1	2.8
part of	-2.4	3.2	2.7	-1.5	3.0	-2.4	-0.6	-2.6	2.9	-1.9
has part	-2.5	3.2	2.9	-1.5	3.0	2.4	0.7	2.8	-3.0	1.9
member holonym	2.4	2.8	2.4	1.9	-2.4	-2.9	-2.3	2.6	2.7	-2.4
member meronym	2.4	2.9	2.4	1.9	-2.3	-2.9	2.3	-2.5	-2.8	2.5
synset domain region of	-3.1	-0.3	3.1	-3.3	1.9	-0.9	2.0	-2.1	-1.2	1.0
member of domain region	-3.1	-0.3	3.2	-3.4	2.0	1.0	-2.1	2.2	1.3	-1.1
verb group	3.5	3.4	3.3	-1.8	-2.8	0.0	-0.1	0.0	0.0	0.0
derivationally related form	3.5	3.4	-3.2	3.4	3.2	0.0	0.0	-0.0	0.0	0.0

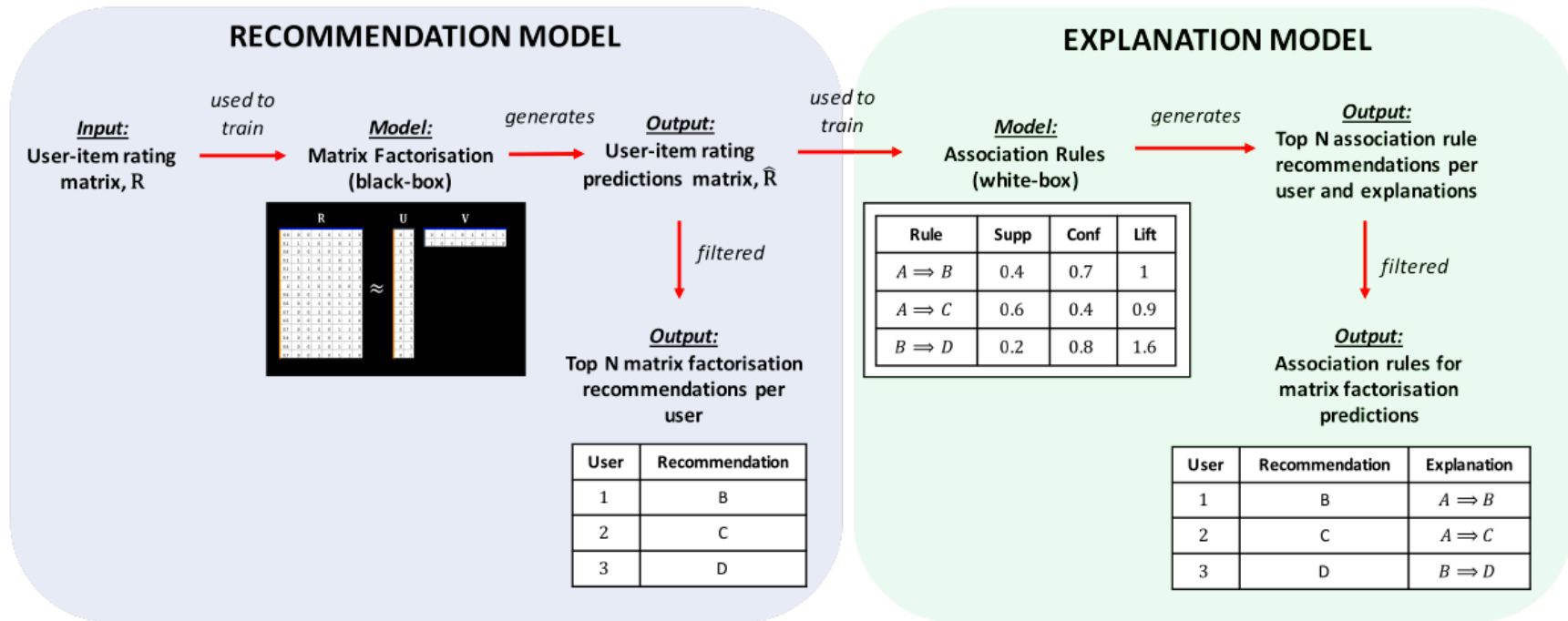
	Real Part					Imaginary Part				
musical artist	1.9	3.8	3.8	-1.7	-1.0	-2.5	0.4	-0.8	3.0	3.7
musical band	1.8	3.8	4.1	-1.8	-1.0	-2.5	0.3	-0.9	3.1	3.6
associated musical artist	3.7	3.2	3.7	3.4	3.3	0.7	0.1	0.2	-1.5	1.5
associated band	3.7	3.7	3.2	3.7	3.6	0.7	0.0	0.2	-1.5	1.5

	Real Part					Imaginary Part				
playsFor	3.6	-2.6	2.6	2.7	-3.1	2.5	3.0	2.8	2.6	-2.6
isAffiliatedTo	3.8	-2.6	2.6	2.6	-3.2	2.7	3.3	3.0	2.6	-2.8
hasNeighbor	0.9	2.5	2.9	3.5	2.2	0.0	-0.0	0.0	-0.1	-0.0
isMarriedTo	3.9	3.5	4.3	-2.1	0.0	0.0	-0.0	-0.0	0.0	0.0
isConnectedTo	-0.7	3.0	2.6	0.3	2.7	0.3	-0.1	-0.0	0.1	-0.0



# Latent Feature Models - Post Hoc Interpretability

Generate an explanation model by training Bayesian Networks or Association Rules on the output of a Latent Feature Model. [Carmona et al. 2015, Peake et al. KDD 2018, Gusmão et al. 2018]



# Combining Observable and Latent Feature Models

- **Additive Relational Effects (ARE)** [Nickel et al. NeurIPS 2014] — combines Observable and Latent Features in a single linear model:

$$f_{spo}^{ARE} = \mathbf{w}_{LFM,p}^\top \Theta_{LFM,so} + \mathbf{w}_{OBS,p}^\top \Theta_{PRA,so}$$

- **Knowledge Vault** [Dong et al. KDD 2014] — combines the prediction of Observable and Latent Feature Models via *stacking*:

$$f_{spo}^{KV} = f_{FUSION} \left( f_{spo}^{OFM}, f_{spo}^{LFM} \right)$$

- **Adversarial Sets** [Minervini et al. UAI 2017] — incorporate observable features, in the form of *First-Order Logic Rules*  $R$ , in Latent Feature Models:

$$\mathcal{L}(\Theta \mid R) = \mathcal{L}_{LFM}(\Theta) + \max_{\mathcal{S} \subseteq \mathcal{P}(\mathcal{E})} \mathcal{L}_{RULE}(\Theta, R)$$

# End-to-End Differentiable Reasoning

We can combine *neural networks* and *symbolic models* by re-implementing classic reasoning algorithms using end-to-end differentiable (neural) architectures:

## Differentiable Architectures

- Can generalise from high-dimensional, noisy, ambiguous inputs (*e.g.* sensory)
- Not interpretable
- Hard to incorporate knowledge
- Propositional fixation [McCarthy, 1988]

## Logic Reasoning Based Models

- Can learn from small data
- Issues with high-dimensional, noisy, ambiguous inputs (*e.g.* images)
- Easy to *interpret*, and can provide *explanations* in the form of reasoning steps used to derive a conclusion

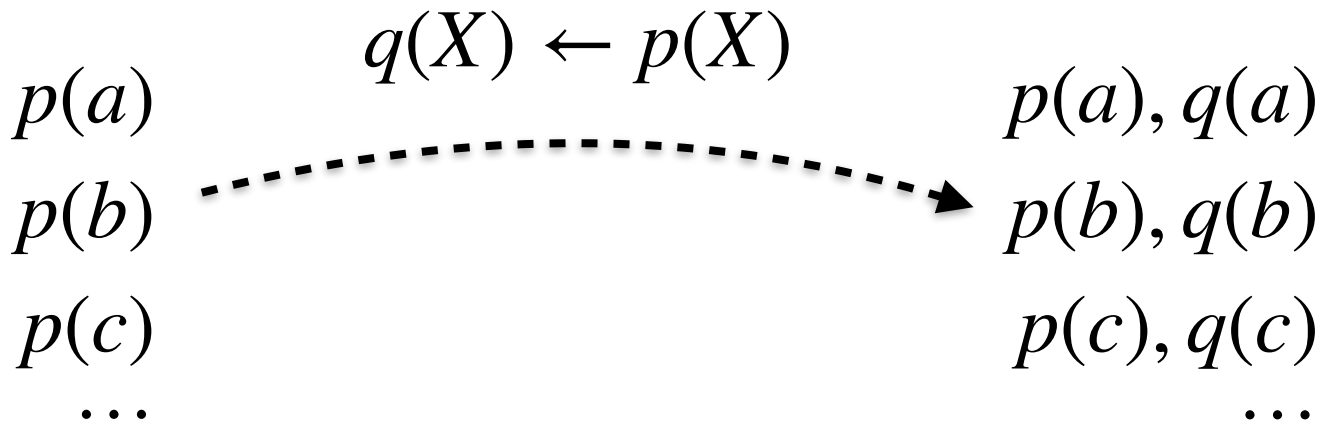
# Reasoning in a Nutshell – Forward Chaining

**Forward Chaining** — start with a list of *facts*, and work forward from the *antecedent*  $P$  to the *consequent*  $Q$  iteratively.

$$\begin{array}{l} p(a) \\ p(b) \\ p(c) \\ \dots \end{array} \qquad q(X) \leftarrow p(X)$$

# Reasoning in a Nutshell – Forward Chaining

**Forward Chaining** — start with a list of *facts*, and work forward from the *antecedent*  $P$  to the *consequent*  $Q$  iteratively.



# Reasoning in a Nutshell — Backward Chaining

**Backward Chaining** — start with a list of *goals*, and work backwards from the *consequent*  $Q$  to the *antecedent*  $P$  to see if any data supports any of the consequents.

$$q(X) \leftarrow p(X)$$

$p(a)$

$q(a)?$

You can see backward chaining as a *query reformulation strategy*.

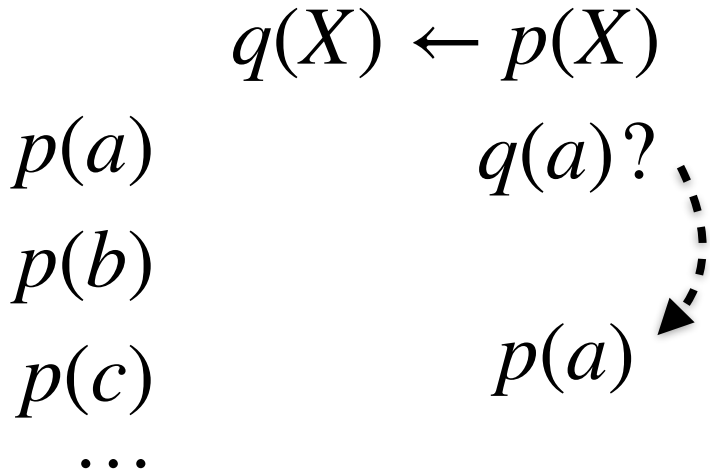
$p(b)$

$p(c)$

...

# Reasoning in a Nutshell — Backward Chaining

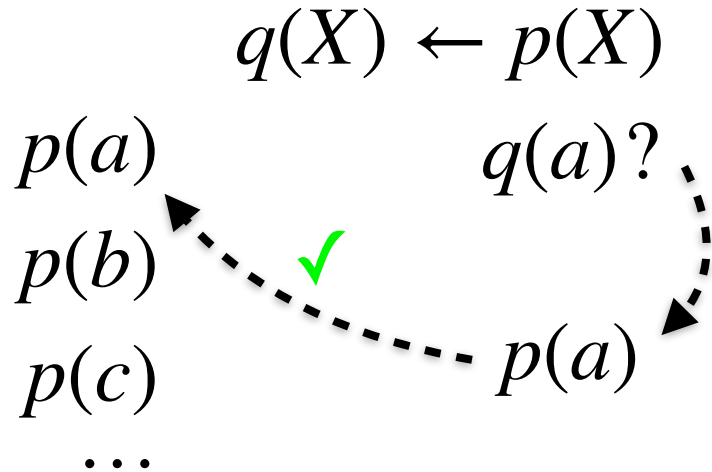
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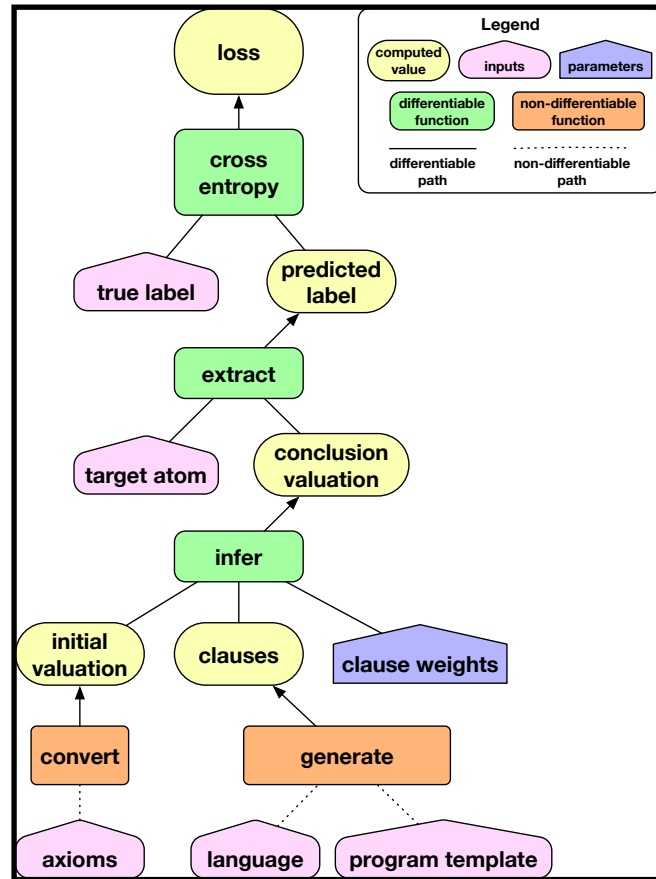


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# Differentiable Forward Chaining - $\partial$ ILP [Evans et al. JAIR 2018]

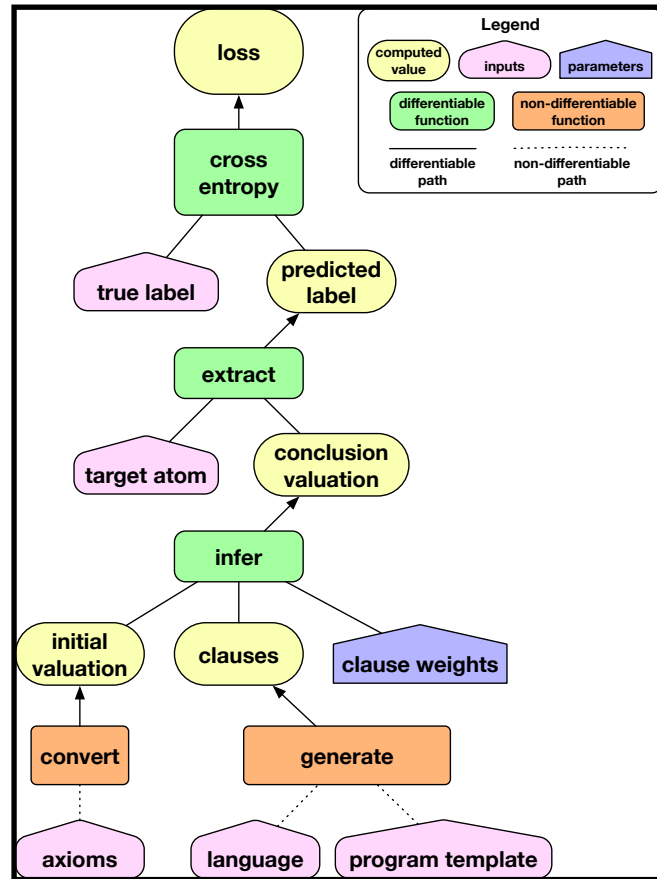
$\partial$ ILP uses a *differentiable model* of forward chaining inference:



# Differentiable Forward Chaining - $\partial$ ILP [Evans et al. JAIR 2018]

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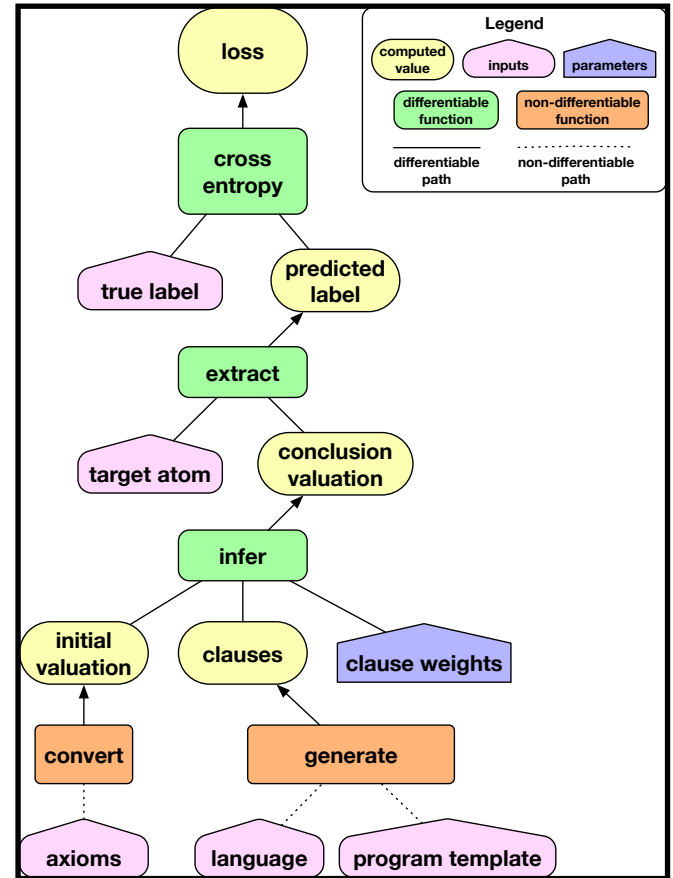
- Weights of the network represent a probability distribution over clauses



# Differentiable Forward Chaining - $\partial$ ILP [Evans et al. JAIR 2018]

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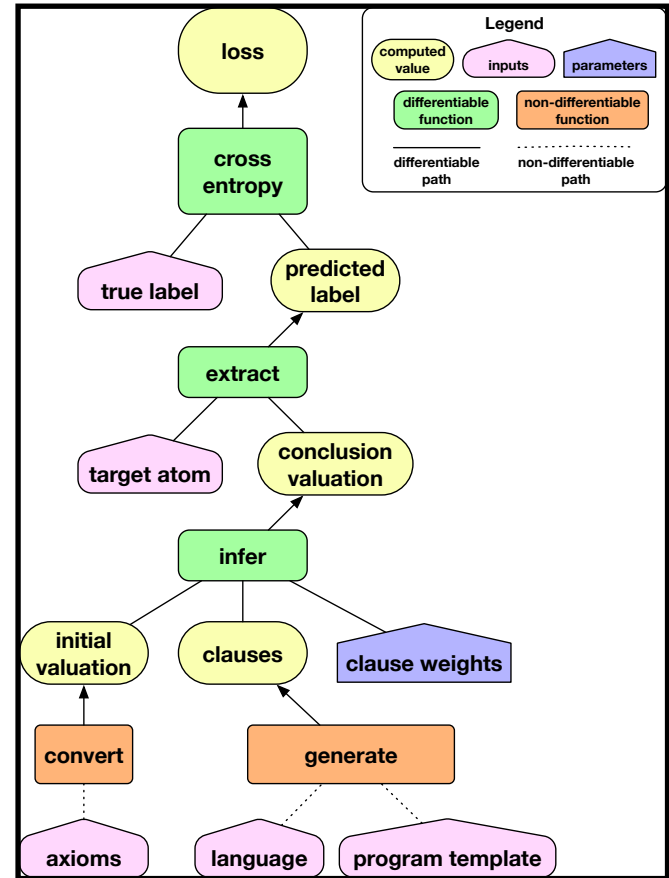
- Weights of the network represent a probability distribution over clauses
- A **valuation** is a vector with values in  $[0, 1]$  representing how likely it is that each of the **ground atoms** is true
- Forward chaining is implemented by a differentiable function that, given a valuation vector, produces another by applying **rules** to it.



# Differentiable Forward Chaining - $\partial$ ILP [Evans et al. JAIR 2018]

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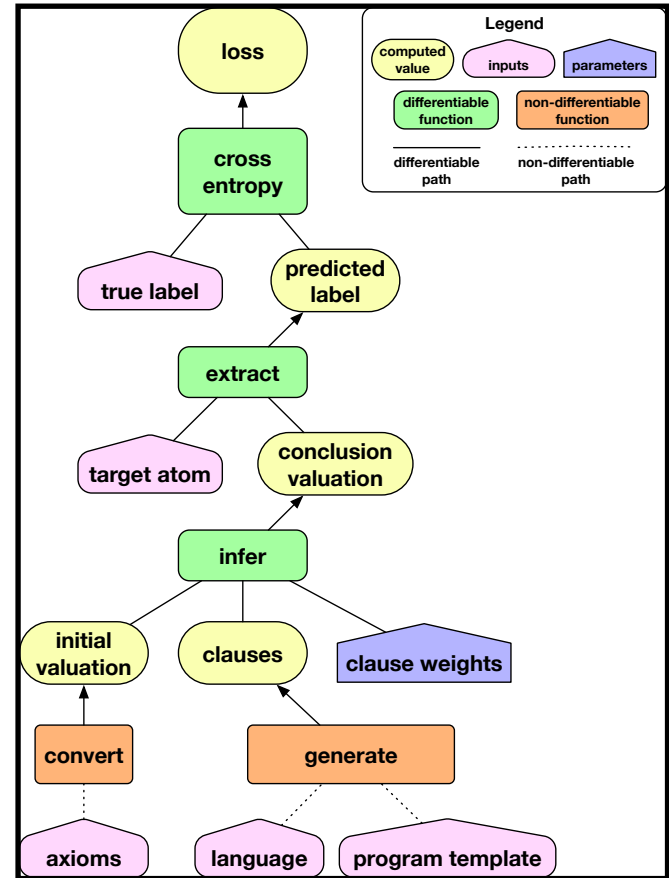


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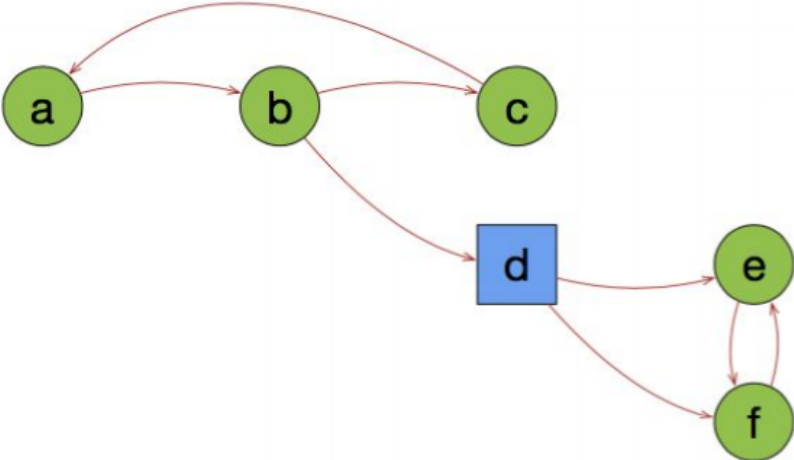
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- Forward chaining is implemented by a differentiable function that, given a valuation vector, produces another by applying **rules** to it.
- If conclusions do not match the desired ones, the error is **back-propagated** to the weights.

We can extract a readable program.



# Differentiable Forward Chaining - $\partial$ ILP [Evans et al. JAIR 2018]



$\text{cycle}(X) \leftarrow \text{pred}(X, X)$   
 $\text{pred}(X, Y) \leftarrow \text{edge}(X, Y)$   
 $\text{pred}(X, Y) \leftarrow \text{edge}(X, Z), \text{pred}(Z, Y)$

# Differentiable Forward Chaining - $\partial$ ILP [Evans et al. JAIR 2018]

1  $\mapsto$  1

2  $\mapsto$  2

3  $\mapsto$  *Fizz*

4  $\mapsto$  4

5  $\mapsto$  *Buzz*

6  $\mapsto$  *Fizz*

7  $\mapsto$  7

8  $\mapsto$  8

9  $\mapsto$  *Fizz*

10  $\mapsto$  *Buzz*

$\text{fizz}(X) \leftarrow \text{zero}(X)$

$\text{fizz}(X) \leftarrow \text{fizz}(Y), \text{pred1}(Y, X)$

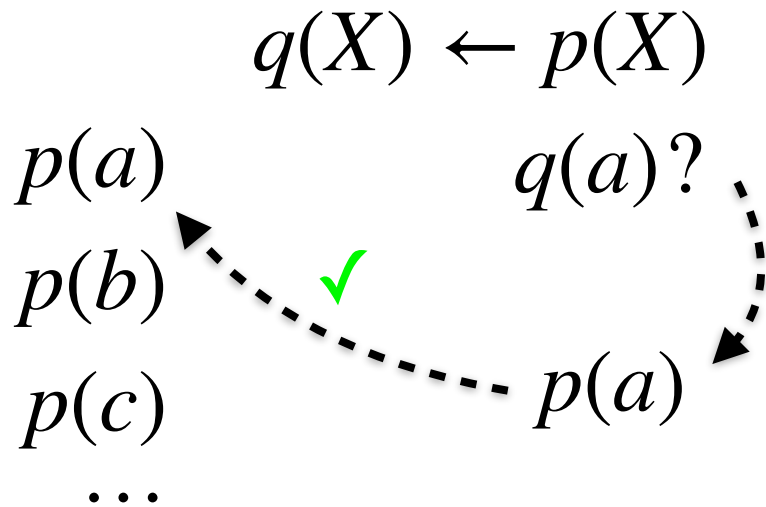
$\text{pred1}(X, Y) \leftarrow \text{succ}(X, Z), \text{pred2}(Z, Y)$

$\text{pred2}(X, Y) \leftarrow \text{succ}(X, Z), \text{succ}(Z, Y)$

# Backward Chaining – Differentiable Proving

[Rocktäschel et al. 2017, Minervini et al. 2018,  
Weiß et al. 2019]

## Backward Chaining

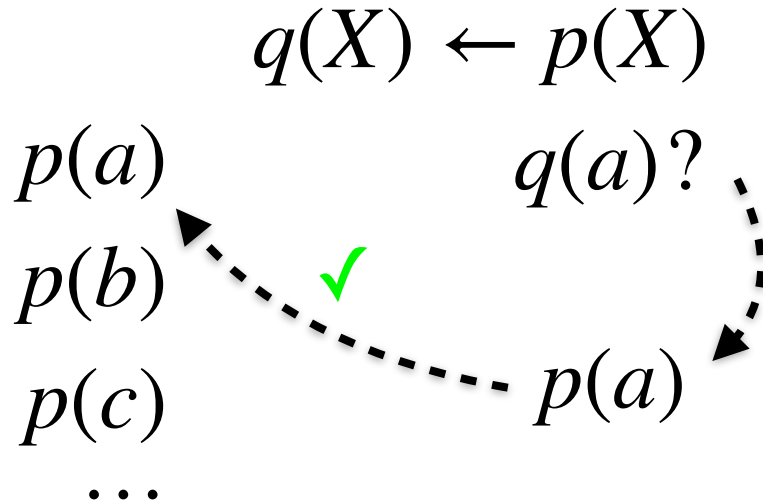




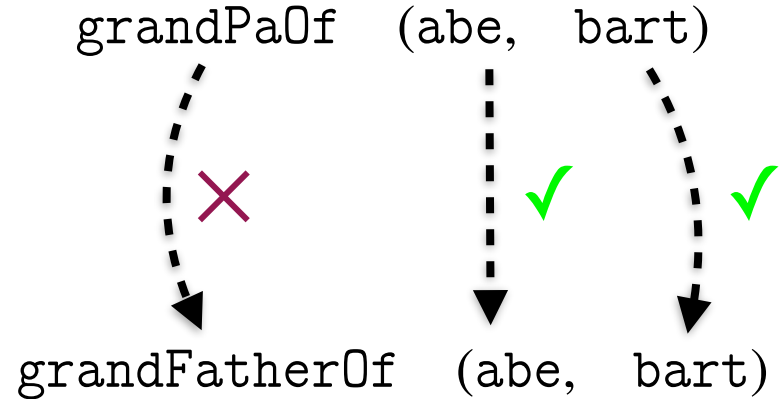
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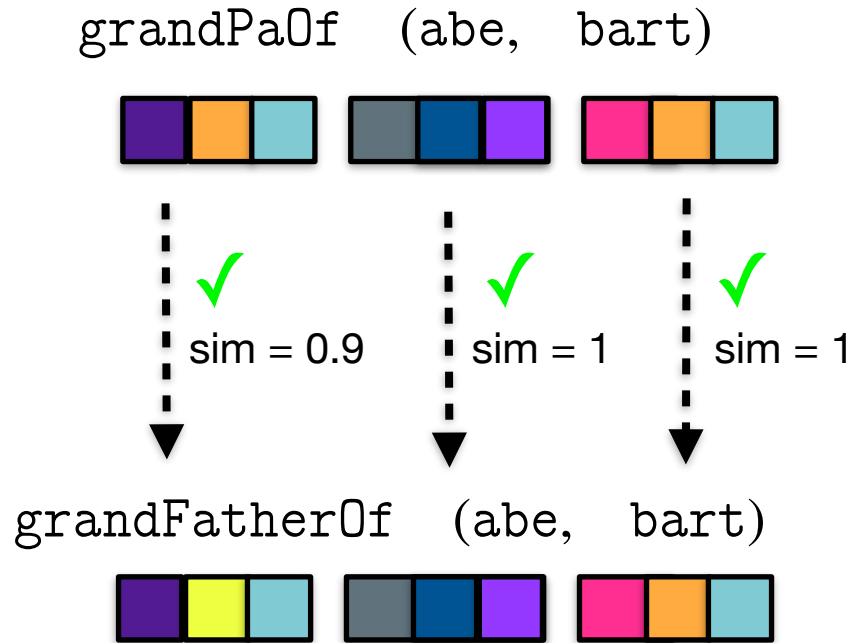


## BUT there's a problem..



# Backward Chaining – Differentiable Proving

[Rocktäschel et al. 2017, Minervini et al. 2018, Webl et al. 2019]



# Backward Chaining – Differentiable Proving

[Rocktäschel et al. 2017, Minervini et al. 2018,  
Weiß et al. 2019]

## Knowledge Base:

fatherOf(abe, homer)

parentOf(homer, bart)

grandFatherOf( $X, Y$ )  $\Leftarrow$

fatherOf( $X, Z$ ),

parentOf( $Z, Y$ ).

grandPaOf(abe, bart)



# Backward Chaining – Differentiable Proving

[Rocktäschel et al. 2017, Minervini et al. 2018, Webl et al. 2019]

## Knowledge Base:

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proof score  $S_1$

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## Knowledge Base:

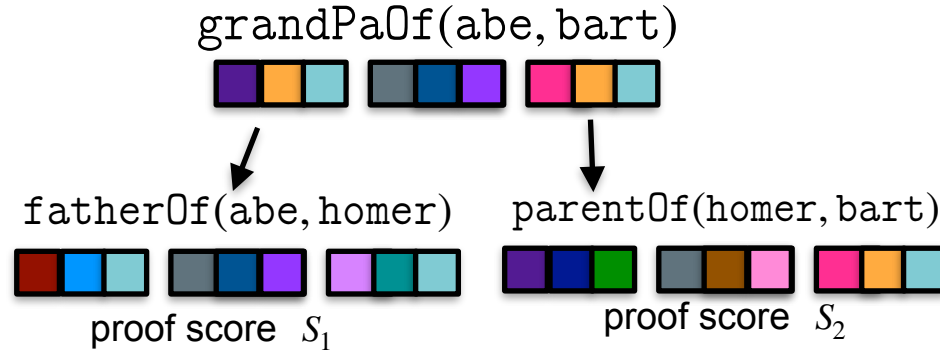
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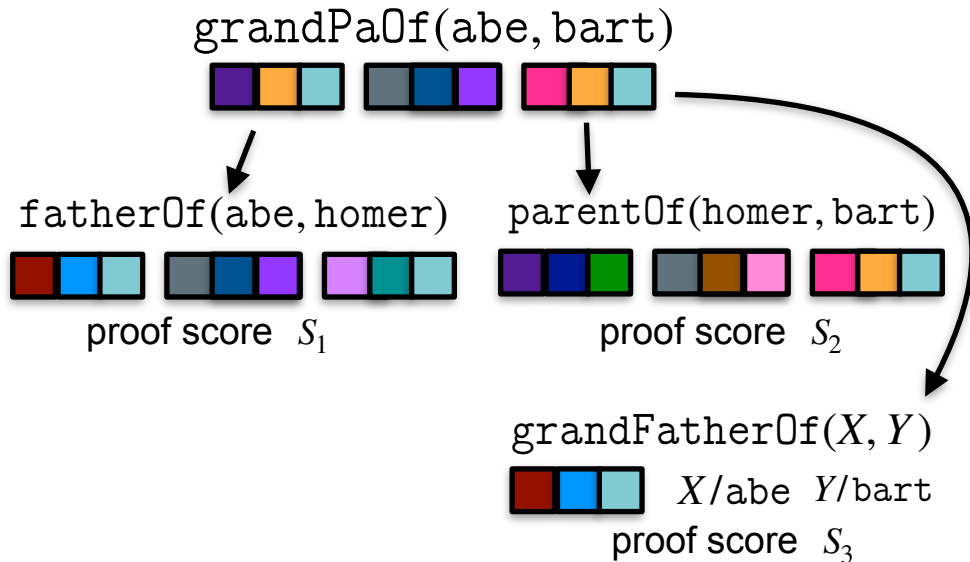
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## Subgoals:

fatherOf(abe, Z)

parentOf(Z, bart)

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[Rocktäschel et al. 2017, Minervini et al. 2018, Webl et al. 2019]

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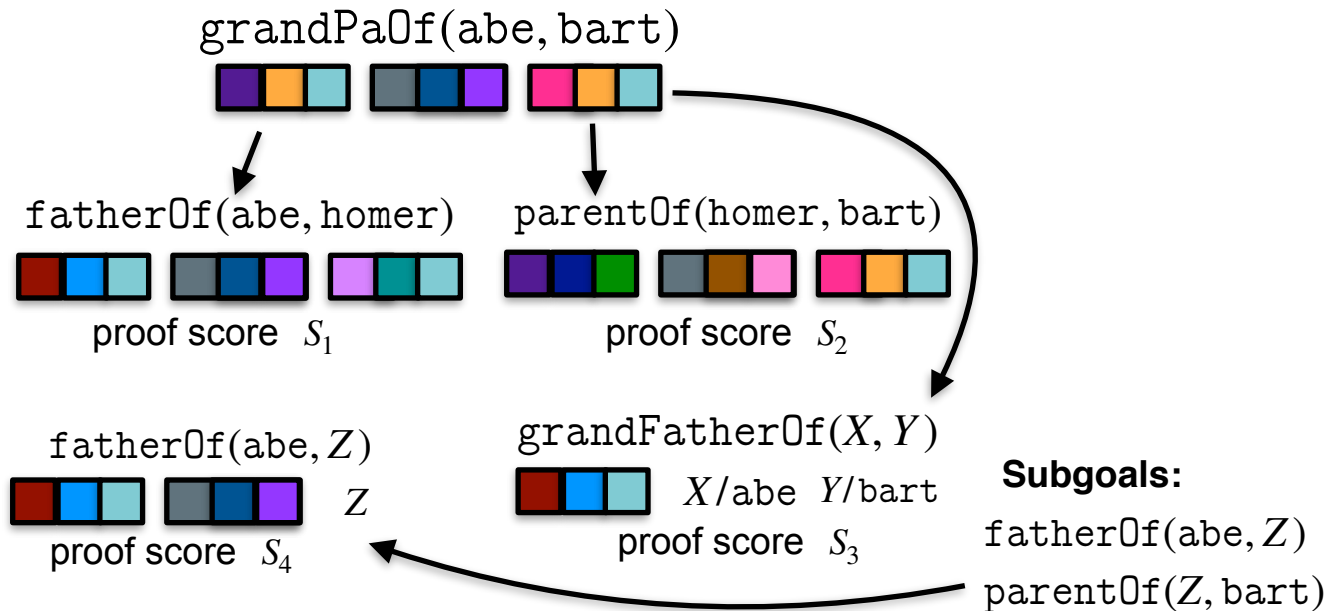
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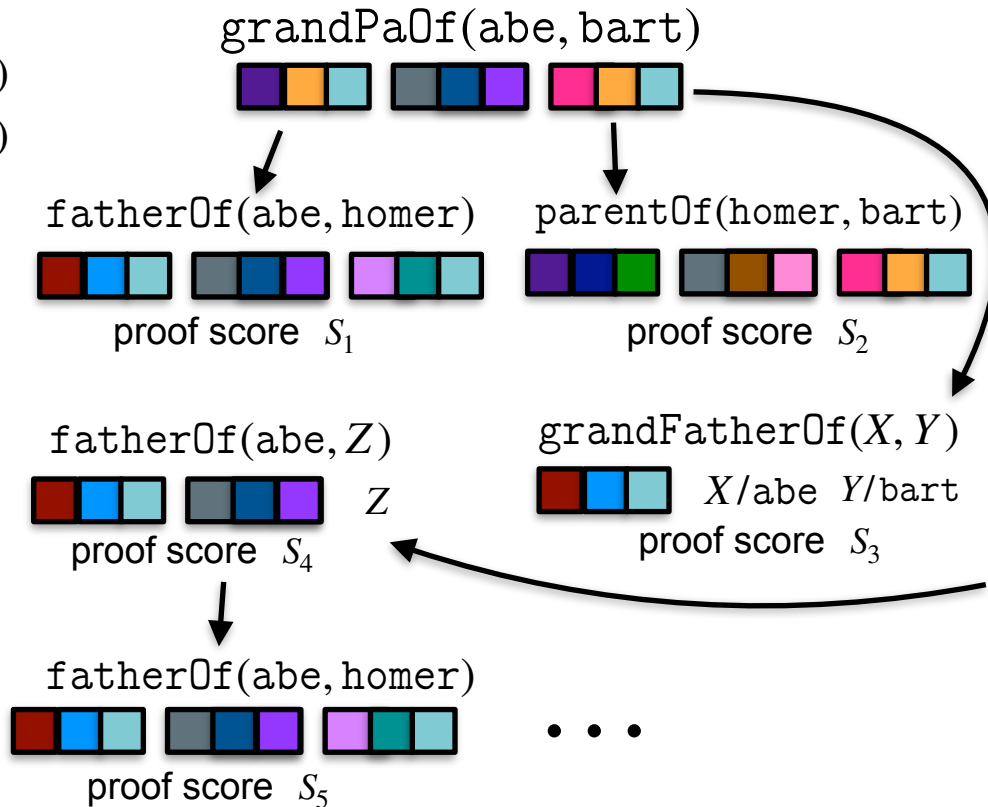
fatherOf(abe, homer)

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grandFatherOf(X, Y)  $\leftarrow$

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parentOf(Z, bart)

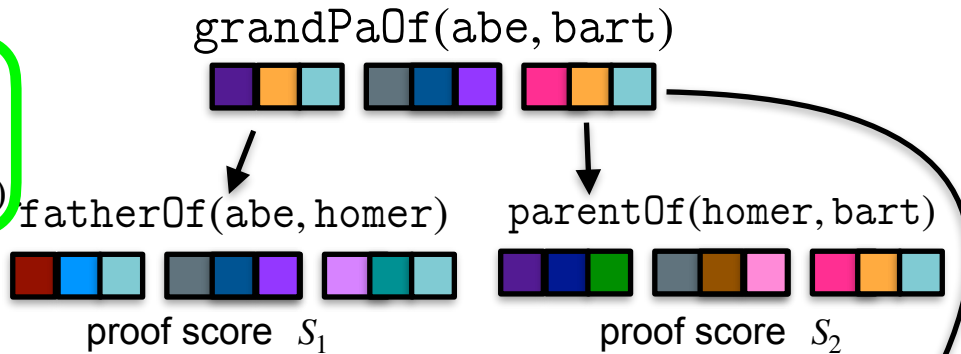


# Learning Interpretable Rules From Data

[Rocktäschel et al. 2017, Minervini et al. 2018, Webl et al. 2019]

## Knowledge Base:

fatherOf(abe, homer)  
 parentOf(homer, bart)  
 $\theta_1(X, Y) \leftarrow \theta_2(X, Z), \theta_3(Z, Y)$

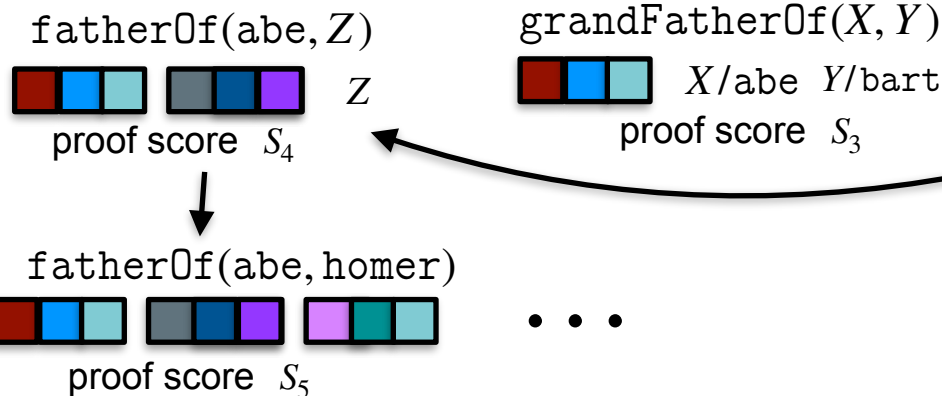


## Training

Maximise Log-Likelihood:

$$\sum_{F \in K} \log p^{KB \setminus F}(F)$$

$$- \sum_{\tilde{F} \sim \text{corr}(F)} \log p^{KB}(\tilde{F})$$



## Subgoals:

fatherOf(abe, Z)  
 parentOf(Z, bart)

# Differentiable Reasoning

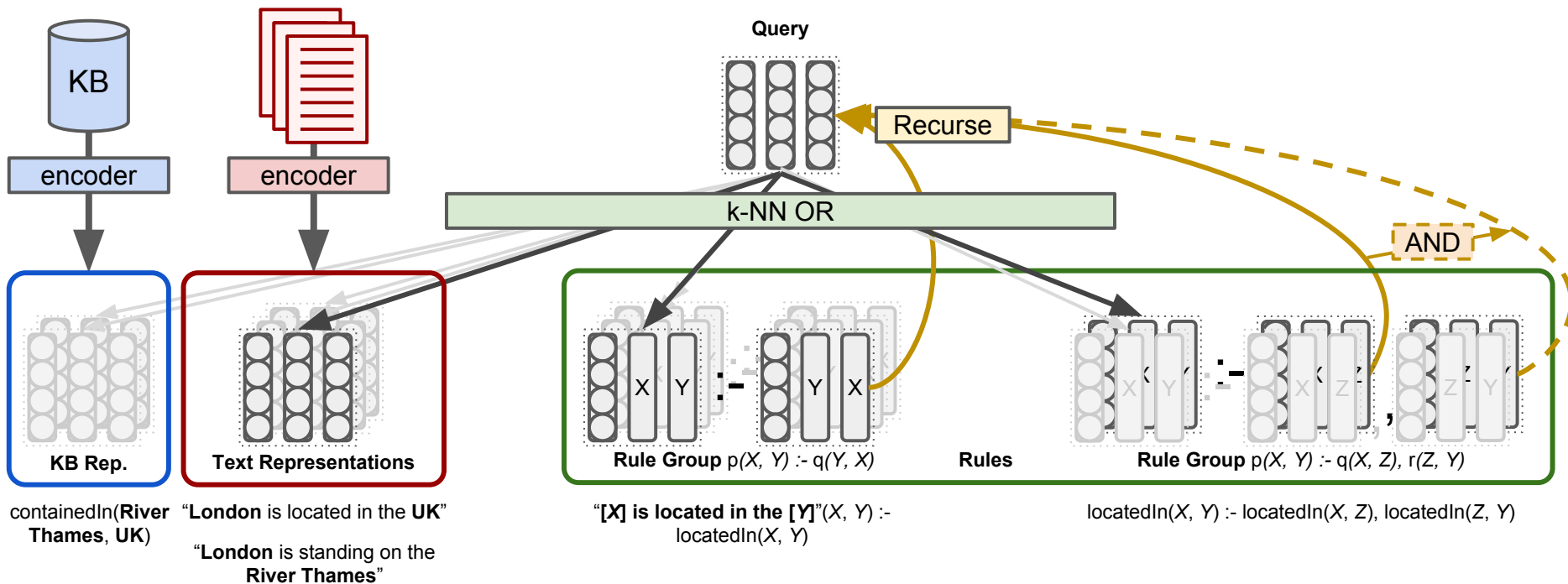
Corpus	Metric	Model			Examples of induced rules and their confidence	
		Complex	NTP	NTP $\lambda$		
Countries	S1	AUC-PR	99.37 $\pm$ 0.4	90.83 $\pm$ 15.4	<b>100.00</b> $\pm$ 0.0	0.90 locatedIn( <b>X</b> , <b>Y</b> ) :- locatedIn( <b>X</b> , <b>Z</b> ), locatedIn( <b>Z</b> , <b>Y</b> ).
	S2	AUC-PR	87.95 $\pm$ 2.8	87.40 $\pm$ 11.7	<b>93.04</b> $\pm$ 0.4	0.63 locatedIn( <b>X</b> , <b>Y</b> ) :- neighborOf( <b>X</b> , <b>Z</b> ), locatedIn( <b>Z</b> , <b>Y</b> ).
	S3	AUC-PR	48.44 $\pm$ 6.3	56.68 $\pm$ 17.6	<b>77.26</b> $\pm$ 17.0	0.32 locatedIn( <b>X</b> , <b>Y</b> ) :- neighborOf( <b>X</b> , <b>Z</b> ), neighborOf( <b>Z</b> , <b>W</b> ), locatedIn( <b>W</b> , <b>Y</b> ).
Kinship	MRR		<b>0.81</b>	0.60	0.80	0.98 term15( <b>X</b> , <b>Y</b> ) :- term5( <b>Y</b> , <b>X</b> )
	HITS@1		0.70	0.48	<b>0.76</b>	0.97 term18( <b>X</b> , <b>Y</b> ) :- term18( <b>Y</b> , <b>X</b> )
	HITS@3		<b>0.89</b>	0.70	0.82	0.86 term4( <b>X</b> , <b>Y</b> ) :- term4( <b>Y</b> , <b>X</b> )
	HITS@10		<b>0.98</b>	0.78	0.89	0.73 term12( <b>X</b> , <b>Y</b> ) :- term10( <b>X</b> , <b>Z</b> ), term12( <b>Z</b> , <b>Y</b> ).
Nations	MRR		<b>0.75</b>	<b>0.75</b>	0.74	0.68 blockpositionindex( <b>X</b> , <b>Y</b> ) :- blockpositionindex( <b>Y</b> , <b>X</b> ).
	HITS@1		<b>0.62</b>	<b>0.62</b>	0.59	0.46 expeldiplomats( <b>X</b> , <b>Y</b> ) :- negativebehavior( <b>X</b> , <b>Y</b> ).
	HITS@3		0.84	0.86	<b>0.89</b>	0.38 negativecomm( <b>X</b> , <b>Y</b> ) :- commonbloc0( <b>X</b> , <b>Y</b> ).
	HITS@10		<b>0.99</b>	<b>0.99</b>	<b>0.99</b>	0.38 intergovorgs3( <b>X</b> , <b>Y</b> ) :- intergovorgs( <b>Y</b> , <b>X</b> ).
UMLS	MRR		0.89	0.88	<b>0.93</b>	0.88 interacts_with( <b>X</b> , <b>Y</b> ) :- interacts_with( <b>X</b> , <b>Z</b> ), interacts_with( <b>Z</b> , <b>Y</b> ).
	HITS@1		0.82	0.82	<b>0.87</b>	
	HITS@3		0.96	0.92	<b>0.98</b>	0.77 isa( <b>X</b> , <b>Y</b> ) :- isa( <b>X</b> , <b>Z</b> ), isa( <b>Z</b> , <b>Y</b> ).
	HITS@10		<b>1.00</b>	0.97	<b>1.00</b>	0.71 derivative_of( <b>X</b> , <b>Y</b> ) :- derivative_of( <b>X</b> , <b>Z</b> ), derivative_of( <b>Z</b> , <b>Y</b> ).

# Explainable Neural Link Prediction

	Query	Score $S_\rho$	Proofs / Explanations
WN18	part_of(CONGO.N.03, AFRICA.N.01)	0.995	part_of( $X, Y$ ) :- has_part( $Y, X$ ) has_part(AFRICA.N.01, CONGO.N.03)
		0.787	part_of( $X, Y$ ) :- instance_hyponym( $Y, X$ ) instance_hyponym(AFRICAN_COUNTRY.N.01, CONGO.N.03)
	hyponym(EXTINGUISH.V.04, DECOUPLE.V.03)	0.987	hyponym( $X, Y$ ) :- hypernym( $Y, X$ ) hyponym(DECOUPLE.V.03, EXTINGUISH.V.04)
		0.920	hyponym(SNUFF_OUT.V.01, EXTINGUISH.V.04)
	part_of(PITUITARY.N.01, DIENCEPHALON.N.01)	0.995	has_part(DIENCEPHALON.N.01, PITUITARY.N.01)
	has_part(TEXAS.N.01, ODESSA.N.02)	0.961	has_part( $X, Y$ ) :- part_of( $Y, X$ ) part_of(ODESSA.N.02, TEXAS.N.01)
	hyponym(SKELETAL_MUSCLE, ARTICULAR_MUSCLE)	0.987	hyponym(ARTICULAR_MUSCLE, SKELETAL_MUSCLE)
deriv_related_form(REWRITE, REWRITING)	0.809	deriv_related_form( $X, Y$ ) :- hypernym( $Y, X$ ) hyponym(REVISE, REWRITE)	
WN18RR	also_see(TRUE.A.01, FAITHFUL.A.01)	0.962	also_see( $X, Y$ ) :- also_see( $Y, X$ ) also_see(FAITHFUL.A.01, TRUE.A.01)
		0.590	also_see(CONSTANT.A.02, FAITHFUL.A.01)
	also_see(GOOD.A.03, VIRTUOUS.A.01)	0.962	also_see(VIRTUOUS.A.01, GOOD.A.03)
		0.702	also_see(RIGHTEOUS.A.01, VIRTUOUS.A.01)
	instance_hyponym(CHAPLIN, FILM_MAKER)	0.812	instance_hyponym(CHAPLIN, COMEDIAN)

# Reasoning Over Text

We can embed facts from the KG and facts from text in a *shared embedding space*, and learn to reason over them *jointly*:



# Reasoning Over Text

[Rocktäschel et al. 2017, Minervini et al. 2018,  
Weiß et al. 2019]

We can embed facts from the KG and facts from text in a *shared embedding space*, and learn to reason over them *jointly*:

Control Myself record\_label Jam Recordings

record\_label(X, Z) ← p<sub>1</sub>(X, Y)

p<sub>1</sub>(X, Z) ← p<sub>2</sub>(X, Y) ∧ p<sub>3</sub>(Y, Z)

Control Myself [...] is a song by american rapper [...] Ell

Ell cools 1989 album [...] was released by [...] Jam Recordings

# Reasoning Over Text

[Rocktäschel et al. 2017, Minervini et al. 2018,  
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We can embed facts from the KG and facts from text in a *shared embedding space*, and learn to reason over them *jointly*:

Thrasylvoulos F.C. country Greece

country(X, Z) ← p<sub>1</sub>(X, Y)

p<sub>1</sub>(X, Z) ← p<sub>2</sub>(X, Y) ∧ p<sub>3</sub>(Y, Z)

Thrasylvoulos Fylis is a football club based in Fyli, Attica [...]

Fyli is a town and a municipality in the northwestern part of Attica, Greece

# Neuro-Symbolic Integration — Recent Advances

- Recursive Reasoning Networks [Hohenecker et al. 2018] — given a OWL RL ontology, uses a differentiable model to update the entity and predicate representations.
- Deep ProbLog [Manhaeve et al. NeurIPS 2018] — extends the ProbLog probabilistic logic programming language with *neural predicates* that can be evaluated on e.g. sensory data (images, speech).
- Logic Tensor Networks [Serafini et al. 2016, 2017] — fully ground First Order Logic rules.
- AutoEncoder-like Architectures [Campero et al. 2018] — use end-to-end differentiable reasoning in the decoder of an autoencoder-like architecture to learn the minimal set of facts and rules that govern your domain via backprop.

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